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Appl. No. 10/520,318  
Amdt. dated March 22, 2007

Reply to Office Action of December 29, 2006  
Attorney Docket 17932

**AMENDMENTS TO THE CLAIMS**

This listing of claims will replace all prior versions, and listings, of claims in the application:

1-9. (Cancelled)

10. (Currently Amended) A method of operating a harvesting machine comprising the steps of:

~~substantially~~-continuously optimizing a stochastic parameter that characterizes the instantaneously prevailing readiness with which the harvesting machine processes crop; and  
~~substantially~~-continuously adjusting a performance variable of the harvesting machine in dependence on the instantaneous, optimized value of said parameter, in order to optimize the a load of the harvesting machine so as to keep a value  $y(t)$  indicative of the effectiveness of said harvesting machine below a predetermined value, wherein the step of adjusting a performance variable of the harvesting machine occurs in dependence on the output of an inverted form of a yield loss estimation function:

$$\hat{y}(t, \theta) = \exp(\theta u(t)) - 1 \quad (B)$$

11. (Original) A method according to Claim 10, wherein:

processing the crop comprises separating useable crop parts from other plant matter;  
optimizing the load of the harvesting machine comprises optimizing the feedrate  $u(t)$  of crop into the harvesting machine; and  
the effectiveness value comprises losses  $y(t)$  of useable crop parts.

12. (Currently Amended) A method according to Claim 10, wherein the step of continuously optimizing a stochastic parameter includes the step of recursively calculating

the optimized parameter value in accordance with the following algorithm:

$$\hat{\theta}(t) = f(\hat{\theta}(t-1), \varepsilon(t, \hat{\theta}(t-1))) \quad - (A)$$

wherein:

$\hat{\theta}(t)$  is the optimized stochastic parameter value at time t; and

$\varepsilon(t, \hat{\theta}(t))$  is an error prediction function

~~carrying out the method steps of Claim 1.~~

13. (Cancelled)

14. (Currently Amended) A method according to Claim 10, wherein adjusting a performance variable comprises adjusting the a travel speed of said harvesting machine or the an actual cutting width of a header of said harvesting machine.

15. (Currently Amended) A method of mapping one or more field lots for variations in a stochastic parameter that characterizes the instantaneously prevailing readiness with which crop is processed in a harvesting machine, the method comprising the steps of:

operating a harvesting machine to harvest crop in a field lot;

simultaneously measuring the a machine load and the machine effectiveness and determining the position of the machine in the field lot;

storing data indicative of the position of the harvesting machine at time t;

using the measured machine load data  $u(t)$ , and machine effectiveness data  $y(t)$  in an optimization of said parameter; and

mapping ~~the~~ optimized parameter values obtained from the step of using the measured machine load data  $u(t)$  and machine effectiveness data  $y(t)$  in an optimization of said parameter; so as to produce a parameter map of the field lot.

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16. (Currently Amended) A method according to Claim 15, wherein the step of using the measured machine load data  $u(t)$ , and machine effectiveness data  $y(t)$  in an optimization of said parameter includes the step of recursively calculating the optimized parameter value in accordance with the following algorithm:

$$\hat{\theta}(t) = f(\hat{\theta}(t-1), \varepsilon(t, \hat{\theta}(t-1))) \quad - (A)$$

wherein:

$\hat{\theta}(t)$  is the optimized stochastic parameter value at time  $t$ ; and

$\varepsilon(t, \hat{\theta}(t))$  is an error prediction function carrying out an optimization according to

Claim 1.

17-21. (Cancelled)